

1. Let $A = \begin{bmatrix} 1 & 3 \\ 1 & -1 \\ 1 & 1 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} 5 \\ 1 \\ 0 \end{bmatrix}$.

- (a) (2 points) Verify that the system $A\mathbf{x} = \mathbf{b}$ is inconsistent.
 (b) (10 points) Find the least-squares solution to $A\mathbf{x} = \mathbf{b}$ in two ways: one that utilizes $\text{proj}_{\text{col}(A)}\mathbf{b}$ and one that utilizes the normal equations. Clearly specify which one is which.
 (c) (2 points) Compute the least-square error of your solution from part (b).

2. Let $A = \begin{bmatrix} 1 & 2 & -9 & 2 \\ 0 & 1 & 6 & 4 \\ 1 & 2 & -6 & 4 \end{bmatrix}$.

- (a) (2 points) Do the columns of A span \mathbb{R}^4 ? Why or why not?
 (b) (2 points) Do the columns of A span \mathbb{R}^3 ? Why or why not?
 (c) (2 points) What is the rank of A ?
 (d) (5 points) Find $\text{Nul}(A)$. Write your answer in set notation.
 (e) (1 point) Check that the vectors found in (d) really are in $\text{Nul}(A)$.

3. Let $T : \mathbf{P}_2 \rightarrow \mathbb{R}^3$ be the linear transformation given by $T(\mathbf{p}(t)) = \begin{bmatrix} \mathbf{p}(-1) \\ \mathbf{p}(0) \\ \mathbf{p}'(-1/2) \end{bmatrix}$.

- (a) (2 points) $\text{Ker}(T)$ is a subspace of _____.
 (b) (5 points) Find the kernel of T . Write your answer in set notation.
 (c) (4 points) Let $\mathcal{B} = \{1, t, t^2\}$. Find the standard matrix of T relative to \mathcal{B} and the standard basis for \mathbb{R}^3 .
 (d) (1 point) In *one* computation, check your answers to (b) and (c).

4. Let

$$\mathbf{a}_1 = \begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix}, \quad \mathbf{a}_2 = \begin{bmatrix} 3 \\ 4 \\ -7 \end{bmatrix}, \quad \mathbf{a}_3 = \begin{bmatrix} -5 \\ -8 \\ 9 \end{bmatrix} \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 4 \\ 7 \\ -6 \end{bmatrix}.$$

- (a) (5 points) Is \mathbf{b} in $\text{span}\{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3\}$?
 (b) (5 points) Could $\{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3\}$ be used as a basis for \mathbb{R}^3 ? Why or why not?

5. Let $\mathbf{p}_1(t) = 1 + t^2$, $\mathbf{p}_2(t) = t$, $\mathbf{p}_3(t) = 1 + t$.

- (a) (5 points) Verify that $\mathcal{B} = \{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3\}$ is a basis of \mathbf{P}_2 .
 (b) (3 points) Find $[3t + 4t^2]_{\mathcal{B}}$.

6. Consider a homogeneous system of 12 linear equations in 14 unknowns whose matrix form is $A\mathbf{x} = \mathbf{0}$.

- (a) (2 points) What is the size of the coefficient matrix A ?

- (b) (4 points) What is the largest that rank (A) can be?
- (c) (4 points) Is it possible that all solutions of $A\mathbf{x} = \mathbf{0}$ are multiples of one fixed nonzero vector? Why or why not?
7. (4 points) Let $W = \left\{ \begin{bmatrix} a & b \\ c & 0 \\ c & 0 \end{bmatrix} : a, b, c \in \mathbb{R} \right\}$. Show that W is a subspace of $M_{3 \times 2}$.
8. Suppose A is a 6×4 matrix whose reduced echelon form has 4 pivots. Let T be the linear transform defined by $T(\mathbf{x}) = A\mathbf{x}$.
- (a) (3 points) What are the domain and codomain of T ?
- (b) (3 points) Is T a one-to-one mapping? Why or why not?
- (c) (3 points) Do the columns of A span the codomain of T ? Why or why not?
9. (a) (2 points) Given three square matrices A , D , and P with P invertible, show that $A = PDP^{-1}$ if and only if $AP = PD$.
- (b) (5 points) Suppose A is the matrix $A = \begin{bmatrix} 7 & 2 \\ -4 & 1 \end{bmatrix}$. Find an invertible matrix P and a diagonal matrix D such that $A = PDP^{-1}$.
- (c) (1 point) Check your answer to (b) by verifying that $AP = PD$.
10. (1 point each) Indicate whether each of the following statements is true or false. You do not need to give explanations as there is no partial credit on this problem.
- (a) If A is an $m \times n$ matrix and A has only the zero vector in its null space, then $\text{rank}(A) = m$.
- (b) If A is an $n \times n$ matrix and one of the eigenvalues of A is 0, then A is not invertible.
- (c) If A is an $n \times n$ matrix with $n - 1$ distinct eigenvalues, then A is not diagonalizable. Assume all entries of A and all eigenvalues are real.
- (d) If A is an $m \times n$ matrix and $\text{rank}(A) = n$, then the system $A\mathbf{x} = \mathbf{b}$ has a solution $\forall \mathbf{b} \in \mathbb{R}^m$.
- (e) If $\hat{\mathbf{x}}$ is a least squares solution to $A\mathbf{x} = \mathbf{b}$, then the least square error is the distance from \mathbf{b} to $\hat{\mathbf{x}}$.
- (f) Let A be an $m \times n$ matrix with $m > n$ and let $\mathbf{b} \in \mathbb{R}^m$. Then there is a unique solution to the least squares problem $A\mathbf{x} = \mathbf{b}$.
- (g) If A can be row-reduced to B , then A and B have the same eigenvalues.
- (h) Every basis for a vector space V contains the same number of elements.
11. (5 points) Suppose $T : V \rightarrow W$ is a linear transformation between vector spaces V and W . Prove that if $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is a linearly **dependent** set in V , then $\{T(\mathbf{v}_1), T(\mathbf{v}_2), \dots, T(\mathbf{v}_k)\}$ is a linearly **dependent** set in W .