

Section 4.1 – Vector Spaces and Subspaces

Main Ideas in this section:

- Definition of a Vector Space
 - Examples of Vector Spaces, old and new
 - Subspaces
 - New look at Span of a set of objects
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A **Vector Space** is a set V of objects for which there are two defined operations, addition and scalar multiplication, subject to the ten rules below. The rules hold for all $\mathbf{u}, \mathbf{v}, \mathbf{w}$ in V and for all scalars c, d in \mathbb{R} .

1. $\mathbf{u} + \mathbf{v} \in V$
2. $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$
3. $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
4. $\exists \mathbf{0} \in V$ such that $\mathbf{u} + \mathbf{0} = \mathbf{u}$
5. $\forall \mathbf{u} \in V, \exists -\mathbf{u} \in V$ such that $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$
6. $c\mathbf{u} \in V$
7. $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$
8. $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$
9. $c(d\mathbf{u}) = (cd)\mathbf{u}$
10. $1\mathbf{u} = \mathbf{u}$

Most obvious example of a vector space: \mathbb{R}^n for any integer n .

Other examples of vector spaces:

- Define $\mathbf{M}_{2 \times 2}$ as

$$\mathbf{M}_{2 \times 2} = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}.$$

$\mathbf{M}_{2 \times 2}$ is a vector space.

- For any integer $n > 0$, define \mathbf{P}_n as the set of all polynomials of degree at most n :

$$\mathbf{P}_n = \{p(t) = a_0 + a_1t + a_2t^2 + \cdots + a_nt^n\}$$

where the coefficients a_0, \dots, a_n are real numbers.

\mathbf{P}_n is a vector space.

- Let V be the set of all real-valued continuous functions $\mathbf{f}(t)$ defined on the interval $[a, b]$. (Take note: This set is generally denoted by $C[a, b]$.) If we define addition and scalar multiplication carefully*, then V is a vector space.

* carefully means: $\mathbf{f} + \mathbf{g}$ is the function whose value at t in the domain is $\mathbf{f}(t) + \mathbf{g}(t)$, and the function $c\mathbf{f}$ is the function whose value at t is $c\mathbf{f}(t)$.

TIP: try to think of an individual object in any vector space as a simple entity, for example as a point in space, even when the object is *not* defined so simply. ** Most Important: every object in a vector space V obeys the ten rules for addition and scalar multiplication as defined for V .

Subspaces– special subsets of Vector Spaces

A **subspace** of a vector space V is a subset H of V that has three properties:

- The zero vector of V is in H .
- H is closed under vector addition. That is, for each \mathbf{u} and \mathbf{v} in H , the sum $\mathbf{u} + \mathbf{v}$ is also in H .
- H is closed under scalar multiplication. That is, for each \mathbf{u} in H and each scalar c , the vector $c\mathbf{u}$ is also in H .

NOTE: Every subspace (not subset) of a vector space is itself a vector space.

Examples of subspaces:

- The set consisting of only the zero vector in any vector space V is a subspace of V . It is called the **zero subspace** and written as $\{\mathbf{0}\}$

- Let $H = \text{span}\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right)$. Then H is a subspace of \mathbb{R}^3 .

Note that H looks and acts like $S = \text{span}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right)$. However, these are fundamentally different spaces. H is a subspace of \mathbb{R}^3 , whereas S is not even a subset of \mathbb{R}^3 .

Exercise: Let H be the set of points inside and on the unit circle in the xy plane. That is, let $H = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x^2 + y^2 \leq 1 \right\}$.

- a. Is H a subset of \mathbb{R}^2 ?
- b. Is H a subspace of \mathbb{R}^2 ?

Exercise: Let H be the set of all polynomials of the form $a + bt^2$, where a and b are in \mathbb{R} .

- a. Is H a subset of \mathbf{P}_2 ?
- b. Is H a subspace of \mathbf{P}_2 ? What if $b = 1$?

Theorem 1 If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ are objects in a vector space V , then $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ is a subspace of V .

$\text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ is called the **subspace spanned** (or **generated**) by $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$. Given any subspace H of V , a **spanning** (or **generating**) **set** for H is a set $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ such that $H = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$

Exercise: Let H be the set of all vectors of the form $(4a + 2b, a + b + c, 0, b - 2c)$. Is H a subspace of the vector space \mathbb{R}^4 ? If so, find its generating set.

Exercise: Let H be the set of all \mathbf{x} in \mathbb{R}^3 such that $A\mathbf{x} = \mathbf{0}$, where $A = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 3 & 3 \\ 0 & 0 & 0 \end{bmatrix}$. Is H a subspace of \mathbb{R}^3 ? If so, find its spanning set.

Exercise: Let H and K be subspaces of a vector space V . The intersection of H and K , denoted $H \cap K$, is the set of \mathbf{v} in V that belong to both H and K . Show that $H \cap K$ is a subspace of V .

Summary

- Vector Space = set of objects with rules for addition and scalar multiplication, and closure under these operations
- Objects in a vector space are not always vectors
- Checking subsets to see if they're subspaces– three criteria
- Span of a set of objects from V is automatically a subspace of V .