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1. (10 points) Given the matrix $A = \begin{pmatrix} 1 & -3 \\ -3 & 1 \end{pmatrix}$ and the eigenvector $\vec{v} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ find
- the eigenvalue λ of A to which \vec{v} corresponds and
 - the associated solution of $D\vec{x} = A\vec{x}$.

Solution: a. $\begin{pmatrix} 1 & -3 \\ -3 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \end{pmatrix} = -2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ so $\lambda = -2$. b. $e^{-2t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

2. (20 points) The 3×3 matrix $A = \begin{pmatrix} 3 & -3 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$ has a triple eigenvalue of 1 (you do not have to verify this). Find the general solution of

$$D\vec{x} = A\vec{x}.$$

Solution: $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$, $\vec{v}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ are (obviously!!) generalized eigenvectors.

Each of these gives a solution $h_i(t) = e^t [I + t(A - I) + \frac{t^2}{2}(A - I)^2] \vec{v}_i =$

$$= e^t \left[\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + t \begin{pmatrix} 2 & -3 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{pmatrix} + \frac{t^2}{2} \begin{pmatrix} 1 & -2 & 1 \\ 1 & -2 & 1 \\ 1 & -2 & 1 \end{pmatrix} \right] \vec{v}_i$$

$$= e^t \begin{pmatrix} 1 + 2t + t^2/2 & -3t - t^2 & t + t^2/2 \\ t + t^2/2 & 1 - t - t^2 & t^2/2 \\ t^2/2 & t - t^2 & 1 - t + t^2/2 \end{pmatrix} \vec{v}_i,$$

so the sought general solution is

$$\vec{x}(t) = c_1 e^t \begin{pmatrix} 1 + 2t + t^2/2 \\ t + t^2/2 \\ t^2/2 \end{pmatrix} + c_2 e^t \begin{pmatrix} -3t - t^2 \\ 1 - t - t^2 \\ t - t^2 \end{pmatrix} + c_3 e^t \begin{pmatrix} t + t^2/2 \\ t^2/2 \\ 1 - t + t^2/2 \end{pmatrix}$$

3. (20 pts) Find the general solution of $\vec{x}' = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \vec{x}$. Hint: $\begin{pmatrix} 1 \\ -i \end{pmatrix}$ is an eigenvector.

Solution: $\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -i \end{pmatrix} = \begin{pmatrix} 1+i \\ * \end{pmatrix} = (1+i) \begin{pmatrix} 1 \\ * \end{pmatrix}$, so the eigenvector $\begin{pmatrix} 1 \\ -i \end{pmatrix}$ corresponds to the eigenvalue $1+i$, and the corresponding (complex) solution is

$$e^{(1+i)t} \begin{pmatrix} 1 \\ -i \end{pmatrix} = e^t (\cos t + i \sin t) \begin{pmatrix} 1 \\ -i \end{pmatrix} = e^t \begin{pmatrix} \cos t + i \sin t \\ \sin t - i \cos t \end{pmatrix} = e^t \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} + i e^t \begin{pmatrix} \sin t \\ -\cos t \end{pmatrix}.$$

The general solution then is $\vec{x}(t) = c_1 e^t \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} + c_2 e^t \begin{pmatrix} \sin t \\ -\cos t \end{pmatrix}$.

4. (20 pts) Find the general solution of $D\vec{x} = A\vec{x} + \begin{pmatrix} e^t \\ e^t \end{pmatrix}$, where $A = \begin{pmatrix} 0 & 2 \\ -1 & 3 \end{pmatrix}$.

Hint: The general solution of $D\vec{x} = A\vec{x}$ is $c_1 e^t \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

Solution: Thanks to the hint we can do variation of parameters right away:

$$\left(\begin{array}{cc|c} 2e^t & e^{2t} & e^t \\ e^t & e^{2t} & e^t \end{array} \right) \rightarrow \left(\begin{array}{cc|c} e^t & 0 & 0 \\ e^t & e^{2t} & e^t \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 0 & 0 \\ e^{-t} & 1 & e^{-t} \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & e^{-t} \end{array} \right),$$

so $c'_1 = 0$ and $c'_2 = e^{-t}$, hence $c_2 = -e^{-t}$, so $c_1 e^t \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} - e^t \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ is the general solution.

5. (20 pts) For the system of differential equations

$$\frac{dx}{dt} = x - y$$

$$\frac{dy}{dt} = -2x + x^2$$

a. find the equilibria. (Make sure to get them right; otherwise there will be little partial credit.)

For each equilibrium

b. state (with reason) whether the Hartman–Grobman Theorem applies,

c. determine its stability,

d. decide whether it is an attractor, a repeller, or neither.

e. Sketch a plausible global phase portrait.

Solution: $\begin{cases} x - y = 0 \\ x(x - 2) = 0 \end{cases}$ gives equilibria $(0, 0)$ and $(2, 2)$. The linearization is $\begin{pmatrix} 1 & -1 \\ 2x - 2 & 0 \end{pmatrix}$.

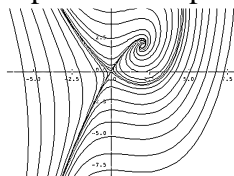
At $(0, 0)$ this matrix becomes $\begin{pmatrix} 1 & -1 \\ -2 & 0 \end{pmatrix}$, whose characteristic polynomial is $(1 - \lambda)(-\lambda) - 2 = (\lambda + 1)(\lambda - 2)$. So $(0, 0)$ is a saddle, hence unstable but neither an attractor nor a repeller. The eigenvalue-eigenvector pairs are -1 , $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$ and 2 , $\begin{pmatrix} -1 \\ 1 \end{pmatrix}$ (no eigenvalues with zero real part, so

the Hartman–Grobman Theorem applies). At $(2, 2)$ the linearization matrix is $\begin{pmatrix} 1 & -1 \\ 2 & 0 \end{pmatrix}$ with

characteristic polynomial $(1 - \lambda)(-\lambda) + 2 = (\lambda - \frac{1}{2})^2 + \frac{7}{4}$, so the eigenvalues are $\frac{1}{2} \pm i\frac{\sqrt{7}}{2}$.

Since both have positive real part, the Hartman–Grobman Theorem applies, $(2, 2)$ is a repeller, hence

unstable.



6. (10 pts) Check whether $E(x, y) = \sin x \sin y$ is a constant of motion for

$$\frac{dx}{dt} = -\sin x \cos y$$

$$\frac{dy}{dt} = \cos x \sin y.$$

Solution: Yes: $\frac{dE}{dt} = -\cos x \sin y \sin x \cos y + \sin x \cos y \cos x \sin y = 0$.