Instructions: No notes or books are allowed. All calculators, cell phones, or other electronic devices **must** be turned off and put away during the exam. Unless otherwise stated, you **must show all work** to receive full credit. You are required to sign your exam. With your signature you are pledging that you have neither given nor received assistance on the exam. Students found violating this pledge will receive an F in the course.

Problem	Point Value	Points
1	6	
2	6	
3	12	
4	12	
5	8	
6	7	
7	14	
8	11	
9	8	
10	16	
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1. (6 pts) Find the inverse of
$$A = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 3 \\ 0 & 1 & 3 \end{bmatrix}$$
.

$$\begin{bmatrix} 1 & 0 & 0 & | & 3 & 1 & -3 \\ 0 & 1 & 0 & | & 3 & 0 & -2 \\ 0 & 0 & 1 & | & -1 & 0 & 1 \end{bmatrix} \quad \text{check} \quad \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 3 \\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} 3 & 1 & -3 \\ 3 & 0 & -2 \\ -1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A^{-1}$$

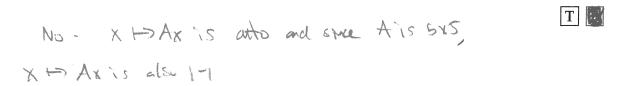
2. (6 pts) T is a linear transformation from \mathbb{R}^2 to \mathbb{R}^2 . Show that T is invertible:

$$T\left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}\right) = \begin{pmatrix} -5x_1 + 9x_2 \\ 4x_1 - 7x_2 \end{pmatrix}$$

Method: Find the stendard motion A of T and show that A is invertible.

$$A = \left(T \begin{pmatrix} 1 \\ 0 \end{pmatrix} + T \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right) = \left(\begin{array}{c} -5 & 9 \\ 4 & -7 \end{array} \right)$$

- 3. (12 pts) **True/false** questions. For each of the statements below, decide whether it is true or false. Indicate your answer by shading the corresponding box. There will be no partial credit.
 - (a) (2 pts) If A is a 5×5 matrix and the equation $A\mathbf{x} = \mathbf{b}$ is consistent for every \mathbf{b} in \mathbb{R}^5 , it is possible that for some \mathbf{b} , the equation $A\mathbf{x} = \mathbf{b}$ has more than one solution.



(b) (2 pts) It is possible for a 4×4 matrix to be invertible when its columns do not span \mathbb{R}^4 .



(c) (2 pts) A square matrix with two identical columns is invertible.



(d) (2 pts) If $A^3 = 0$ then det A = 0.

$$ddA^3 = (det(A))^3$$

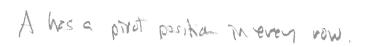
$$det\theta = 0$$



(e) (2 pts) The pivot columns of a matrix are always linearly independent.



(f) (2 pts) If A is $m \times n$ and rank A = m, then the linear transformation $\mathbf{x} \mapsto A\mathbf{x}$ is onto.





4. (12 pts) Suppose that a matrix A is row equivalent to the matrix B given below:

$$B = \begin{bmatrix} 2 & 0 & 3 & -1 \\ 0 & 4 & 1 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 2 & 6 \end{bmatrix} - 2R3 = \begin{bmatrix} 2 & 0 & 3 & -1 \\ 0 & 4 & 1 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} = 0$$
(a) (3 pts) Compute the determinant of B.

(b) (3 pts) Can you compute the determinant of *A*? If so, what is it? If not, why not?

yes -
$$det(A)=0$$
 A \neq I so A is not invertible.
$$\left(A \sim \begin{pmatrix} 2 & 0 & 3 & -1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}\right)$$

Suppose that a matrix C is row equivalent to the matrix D given below:

$$D = \begin{bmatrix} 2 & 0 & 3 & -1 \\ 0 & 4 & 1 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 6 \end{bmatrix}$$

(c) (3 pts) Compute the determinant of D.

(d) (3 pts) Can you compute the determinant of *C*? If so, what is it? If not, why not?

5. (8 pts)

- (a) (4 pts) Define what it means for a subset H to be a subspace of a vector space V.
- 1) Or EH
- 2) Far all 4,0 EH, 440 EH
- 3) For all WEH, Scalars C, CLEH.

(b) (4 pts) Let V be a vector space and let $\mathcal{B} = \{v_1, v_2, ..., v_p\}$ be an indexed set of vectors in V. Complete the following: \mathcal{B} is called a basis for V if:

1) B is linearly independent

2) B spars V

- 6. (7 pts) Prove whether each of the following sets is a subspace. **If it does form a subspace, determine its dimension.**
 - (a) (3 pts) $\{p(t) \in \mathbb{P}_3 : p(2) = 2\} \subseteq \mathbb{P}_3$

Not a subspece since of & of this set.

Of $(\pm 1)=0$ for all \pm so $O_{R_3}(z)=0$, not 2.

(b) (4 pts)
$$W = \left\{ \begin{bmatrix} 2t+2\\t+1\\0\\-t-1 \end{bmatrix} : t \in \mathbb{R} \right\} \subseteq \mathbb{R}^4$$

$$N: \begin{cases} \binom{2+1}{t} + \binom{2}{t} \\ \binom{1}{t} + \binom{2}{t} \end{cases}$$

$$= \left\{ \left\{ \left\{ \begin{array}{c} 2 \\ 1 \\ 0 \\ -1 \end{array} \right\} + \left\{ \left\{ \begin{array}{c} 2 \\ 1 \\ 0 \end{array} \right\} \right\} + \left\{ \left\{ \begin{array}{c} 2 \\ 1 \\ 0 \end{array} \right\} \right\} \right\}$$

$$= \left. \left\{ \begin{array}{c} 2 \\ 1 \\ -1 \end{array} \right\} : S \in \mathbb{R} \right\} = \left. \begin{array}{c} 2 \\ 1 \\ 0 \\ -1 \end{array} \right\}$$

i. W is a subspace of TRY.

A Hernste Solvan to 606)
$$W = \left\{ \begin{pmatrix} 24+2\\ 4+1\\ -4-1 \end{pmatrix} : terr \right\} \leq R^4$$

$$|u+v| = \begin{cases} 2a+2+2b+2 \\ a+1+b+1 \\ 0 \\ -a-b-2 \end{cases} = \begin{cases} 2a+b+1 \\ 2a+b+1 \\ 0 \\ -a-b-2 \end{cases} = \begin{cases} 2a+b+1 \\ 2a+b+1 \\ 0 \\ -a-b-1 \\ 0 \end{cases} = \begin{cases} 2a+b+1 \\ 2a+b+1 \\ 0 \\ -a-b-1 \\ 0 \end{cases}$$

-C6 - C + 1 1

$$CU = C \begin{vmatrix} 2a+2 \\ a+1 \\ 0 \\ -a-1 \end{vmatrix} = \begin{vmatrix} 2ca+2c \\ ca+c \\ -b-1 \end{vmatrix} = \begin{vmatrix} 2d+1 & 2 \\ 2d+1 & 2 \\ -ca-c \\ -d-1 \end{vmatrix} = \begin{vmatrix} 2ca+2c \\ -d-1 \\ -d-1 \end{vmatrix} = \begin{vmatrix} 2ca+2c \\ -d-1 \\ -d-1 \end{vmatrix} = \begin{vmatrix} 2ca+2c \\ -d-1 \\ -d-1 \end{vmatrix}$$

7. (14 pts) Let $T: \mathbb{P}_2 \to \mathbb{R}^2$ be the transformation defined by

$$p(t) \mapsto \begin{bmatrix} p(0) \\ p''(0) \end{bmatrix}$$

where p'' denotes the second derivative of p.

(a) (8 pts) Prove that T is a linear transformation.

Then
$$T(\rho+q) = T(\rho) + T(q)$$
 where $\rho, q \in P_2$

$$T((\rho+q)(+1)) = \begin{bmatrix} (\rho+q)(0) \\ (\rho+q)'(0) \end{bmatrix} = \begin{bmatrix} \rho(0) + q(0) \\ \rho''(0) + q''(0) \end{bmatrix} = \begin{bmatrix} \rho(0) \\ \rho''(0) \end{bmatrix} + \begin{bmatrix} q(0) \\ q''(0) \end{bmatrix}$$

$$= T(\rho) + T(q)$$

2) Show $T(c\rho) = cT(\rho)$ where $\rho \in P_2$, C is a scolar

$$T((C\rho)(+1)) = \begin{bmatrix} (c\rho)(0) \\ (c\rho)''(0) \end{bmatrix} = \begin{bmatrix} (c,\rho)(0) \\ (c,\rho)''(0) \end{bmatrix} = C \begin{bmatrix} \rho(0) \\ (c,\rho)''(0) \end{bmatrix} = C T(\rho)$$

(b) (6 pts) Find a basis for the kernel of T.

Let
$$p|H|=a+b++c+^2 \in \mathbb{F}_2$$
. Then $p|D|=a$, $p'(H)=b+2c+$

$$p''(H)=b+2c+$$

$$T(p(H))=\begin{bmatrix} a \\ 2c \end{bmatrix}$$

$$T(p(H))=\begin{bmatrix} a \\ b \end{bmatrix} \iff q=0 \text{ and } 2l=0 \Rightarrow l=0$$

$$\therefore p(H) \in \ker T \iff p(H)=b+1$$
One basis for Kent is $B=\{+\}$

8. (11 pts) Consider the matrix

$$A = \begin{bmatrix} 7 & 7 & 7 & 7 \\ 2 & 0 & 4 & 0 & 3 \\ 1 & 1 & 2 & 2 & 0 \\ 0 & 1 & 0 & 2 & 1 \\ 0 & -1 & 0 & -2 & -1 \end{bmatrix} \text{ and its row equivalent matrix } B = \begin{bmatrix} 7 & 7 & 7 & 7 \\ 1 & 0 & 2 & 0 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

(a) (3 pts) Find a basis for Col A and determine its dimension.

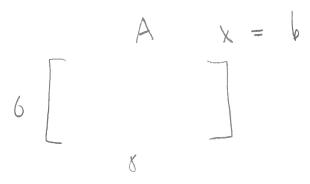
$$\mathcal{B}_{COLA} = \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 1 \\ 1 \end{pmatrix}$$
 due $COLA = 3$

(b) (3 pts) Find a basis for
$$\operatorname{Nul} A$$
 and determine its dimension.

(c) (3 pts) Find a basis for Row A and determine its dimension.

(d) (2 pts) How many pivot columns are in a row echelon form of A^T ? Explain.

9. (8 pts) Suppose a nonhomogeneous system of six equations of eight unknowns has a solution for all possible constants on the right sides of the equations. Is it possible to find two nonzero solutions of the associated homogeneous system that are not multiples of each other? Explain.



Given: Ax=b has a solution for all b ERB > A has
pivot position in all 6 rows > A has 6 pivot rolum) and
Ax=0 has exactly 2 from variables.

Small Ax=0 has except 2 there severbles, dim Noll A = 2.

Thus Noll A has a basis of size 2 and these 2 vectors

Softs for the condition of being 2 non-0 Chitian that are

LI (not multiples)

JES

10. (16 pts) Let V be the set of all 2×2 matrices.

Let *H* be the subspace of *V* with a basis $\mathcal{B} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ and consider the ordered set,

$$S = \{u, v, w\} = \left\{ \begin{bmatrix} -6 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 4 & 5 \\ 0 & 10 \end{bmatrix}, \begin{bmatrix} -2 & 10 \\ 0 & 20 \end{bmatrix} \right\}.$$

(a) (4 pts) Write $[u]_{\mathcal{B}}$, $[v]_{\mathcal{B}}$, and $[w]_{\mathcal{B}}$ in \mathcal{B} -coordinate vectors.

$$\begin{bmatrix} a \end{bmatrix}_{B} = \begin{pmatrix} -6 \\ 0 \\ 0 \end{pmatrix} \qquad \begin{bmatrix} v \end{bmatrix}_{B} = \begin{pmatrix} 4 \\ 5 \\ 10 \end{pmatrix} \qquad \begin{bmatrix} w \end{bmatrix}_{B} = \begin{pmatrix} -2 \\ 10 \\ 20 \end{pmatrix}$$

(b) (8 pts) Is
$$S = \{u, v, w\} = \left\{ \begin{bmatrix} -6 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 4 & 5 \\ 0 & 10 \end{bmatrix}, \begin{bmatrix} -2 & 10 \\ 0 & 20 \end{bmatrix} \right\}$$
 linearly independent? Explain.

(ansider $S' = \left\{ \begin{bmatrix} u \\ b \end{bmatrix}_{\mathcal{B}}, \begin{bmatrix} u \\ b \end{bmatrix}_{\mathcal{B}}, \begin{bmatrix} u \\ b \end{bmatrix}_{\mathcal{B}} = \left\{ \begin{bmatrix} -6 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 4 & 5 \\ 0 & 10 \end{bmatrix}, \begin{bmatrix} -2 & 10 \\ 0 & 20 \end{bmatrix} \right\}$

Since the coordinate mapping is an isomorphism, S is LT and S' is LT.

Let $A = \begin{pmatrix} -6 & 4 & 2 \\ 0 & 5 & -10 \\ 0 & 10 & 20 \end{pmatrix} \sim \begin{pmatrix} -6 & 4 & 2 \\ 0 & 5 & -10 \\ 0 & 0 & 0 \end{pmatrix}$ The column of A are LD since A and A are LD.

(Problem 10 continues on the next page)

(Problem 10 continues)

(c) (4 pts) Find a basis for the subspace spanned by S.

The 3 vectors is an LD but no 2 are miltiples of each other and now are Q. Chapter on 2 for a bear - e.s $B = \left\{ \begin{pmatrix} -6 & c \\ 0 & 6 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} \right\}$